

# Performance and Safety Enhancement Strategies in Vehicle Dynamics and Ground Contact

Edited by

Flavio Farroni, Andrea Genovese and Aleksandr Sakhnevych Printed Edition of the Special Issue Published in *Applied Sciences* 



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### **About the Editors**

Flavio Farroni is a Professor of Applied Mechanics at the University of Naples; founder and CEO of its spinoff, MegaRide; and works as an academic advisor in vehicle dynamics with several companies and racing teams. He works on the development of physical models for the optimization of performance in motorsports, in Drivers in the Loop systems and in digital mobility scenarios, cooperating within an international research network. During TireExpo2015, he received the "Young Scientist of the Year" award from MIT Technology Review, was among "Italian Innovators Under 35" of 2018, and as the start-up of MegaRide, won "Tire Technology of the Year" at the 2018 Tire Technology Conference.

Andrea Genovese received an M.S. in Mechanical Engineering (summa cum laude) and PhDs in Industrial Engineering from the University of Naples, in 2011 and 2018, respectively. He is Assistant Professor in Applied Mechanics to Machines at the University of Naples Federico II. His research interests include the design and development of mechatronic systems, smart systems, tribology, non-destructive materials characterization, energy harvesting, vehicle dynamics and vibration control. He is author of more than 30 papers in international journals and refereed conferences. He serves on the Editorial Board of several international scientific journals and conferences.

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## Preface to "Performance and Safety Enhancement Strategies in Vehicle Dynamics and Ground Contact"

This book was created with the aim of collecting the latest and most interesting advances in the research domain the guest editors' scientific and technical activities are focused towards.

We hope that it serves as a useful contribution to the state-of-the-art developments in vehicle dynamics, which nowadays concern onboard controls and computational science, attracting experimental and in-simulation papers, focusing on both basic research and perspective applications for future mobility. This book's articles involve research, studies, and projects derived from vehicle dynamics and contact mechanics, with the outlook of embracing activities that aim to enhance vehicle performance in terms of handling, comfort, and adherence and to examine safety optimization in the emerging contexts of smart, connected, and autonomous driving.

Our work on the editing of the volume allowed us to get in touch with brilliant scientists and professionals from the automotive community, providing further value to this challenging research topic.

Our sincere thanks go to all of them for their contributions and to the MDPI Editorial Office, with particular reference to Ms. Shirley Wang, who provided continuous and extensive support.

Flavio Farroni, Andrea Genovese, Aleksandr Sakhnevych

Editors